

# Assignment #5 - Spring/2019

## Assignment 5 (sections 2.5, 2.6, 2.7, 3.1)

Due: February 27, 2019

Term: Spring, 2019

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[First Name]

[Last Name]

[Net ID]

### Suggested problems (do not turn in):

Section 2.5: 1, 5, 6, 7, 10, 11, 12, 13, 18, 22, 25, 27, 29, 44.

Section 2.6: 1, 3, 4, 6, 8, 9, 10, 13, 14, 17, 22, 23.

Section 2.7: 1, 2, 3, 4, 5, 6, 7, 8, 9, 10, 11, 20, 21, 22, 23.

Section 3.1: 1, 2, 5, 9, 10, 11, 12, 19, 20, 24, 26.

Note that solutions to these suggested problems are available at [math.mit.edu/linearalgebra](http://math.mit.edu/linearalgebra)

1. [10 points] Use the Gauss-Jordan method to find the inverse of  $A = \begin{bmatrix} 1 & -1 & 0 \\ 1 & 0 & -1 \\ -6 & 2 & 3 \end{bmatrix}$ .

### Solution:

$$\begin{aligned} [A | I] &= \left[ \begin{array}{ccc|ccc} 1 & -1 & 0 & 1 & 0 & 0 \\ 1 & 0 & -1 & 0 & 1 & 0 \\ -6 & 2 & 3 & 0 & 0 & 1 \end{array} \right] \xrightarrow[\begin{array}{l} R_2 - R_1 \\ R_3 + 6R_1 \end{array}]{\begin{array}{l} R_2 - R_1 \\ R_3 + 6R_1 \end{array}} \left[ \begin{array}{ccc|ccc} 1 & -1 & 0 & 1 & 0 & 0 \\ 0 & 1 & -1 & -1 & 1 & 0 \\ 0 & -4 & 3 & 6 & 0 & 1 \end{array} \right] \xrightarrow{R_3 + 4R_2} \left[ \begin{array}{ccc|ccc} 1 & -1 & 0 & 1 & 0 & 0 \\ 0 & 1 & -1 & -1 & 1 & 0 \\ 0 & 0 & -1 & 2 & 4 & 1 \end{array} \right] \\ &\xrightarrow{R_2 - R_3} \left[ \begin{array}{ccc|ccc} 1 & -1 & 0 & 1 & 0 & 0 \\ 0 & 1 & 0 & -3 & -3 & -1 \\ 0 & 0 & -1 & 2 & 4 & 1 \end{array} \right] \xrightarrow{R_1 + R_2} \left[ \begin{array}{ccc|ccc} 1 & 0 & 0 & -2 & -3 & -1 \\ 0 & 1 & 0 & -3 & -3 & -1 \\ 0 & 0 & -1 & 2 & 4 & 1 \end{array} \right] \\ &\xrightarrow{(-1)R_3} \left[ \begin{array}{ccc|ccc} 1 & 0 & 0 & -2 & -3 & -1 \\ 0 & 1 & 0 & -3 & -3 & -1 \\ 0 & 0 & 1 & -2 & -4 & -1 \end{array} \right] \Rightarrow A^{-1} = \begin{bmatrix} -2 & -3 & -1 \\ -3 & -3 & -1 \\ -2 & -4 & -1 \end{bmatrix} \end{aligned}$$

2. [10 points] Consider  $A = \begin{bmatrix} 1 & 3 \\ 2 & 8 \end{bmatrix}$ .

(a) (2 points). Use elementary row operations to reduce  $A$  in to  $I$ .

$$\begin{bmatrix} 1 & 3 \\ 2 & 8 \end{bmatrix} \xrightarrow[E_{21}]{R_2 - 2R_1} \begin{bmatrix} 1 & 3 \\ 0 & 2 \end{bmatrix} \xrightarrow[E_{12}]{R_1 - \frac{3}{2}R_2} \begin{bmatrix} 1 & 0 \\ 0 & 2 \end{bmatrix} \xrightarrow[S_2]{R_2 \rightarrow \frac{1}{2}R_2} \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$$

(b) (2 points). List all corresponding elementary matrices.

$$E_{21} = \begin{bmatrix} 1 & 0 \\ -2 & 1 \end{bmatrix}$$

$$E_{12} = \begin{bmatrix} 1 & -\frac{3}{2} \\ 0 & 1 \end{bmatrix}$$

$$S_2 = \begin{bmatrix} 1 & 0 \\ 0 & \frac{1}{2} \end{bmatrix}$$

(c) (3 points). Find  $A^{-1}$  as a product of elementary matrices.

$$S_2 E_{12} E_{21} A = I \implies A^{-1} = S_2 E_{12} E_{21}$$

$$A^{-1} = \begin{bmatrix} 1 & 0 \\ 0 & \frac{1}{2} \end{bmatrix} \begin{bmatrix} 1 & -\frac{3}{2} \\ 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 \\ -2 & 1 \end{bmatrix} = \begin{bmatrix} 4 & -\frac{3}{2} \\ -1 & \frac{1}{2} \end{bmatrix}$$

(d) (3 points). Express  $A$  as a product of elementary matrices.

$$S_2 E_{12} E_{21} A = I \implies A = E_{21}^{-1} E_{12}^{-1} S_2^{-1}$$

$$A = \begin{bmatrix} 1 & 0 \\ 2 & 1 \end{bmatrix} \begin{bmatrix} 1 & \frac{3}{2} \\ 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 \\ 0 & 2 \end{bmatrix}$$

3. [10 points] Solve the following problems and justify your answers by showing your work.

(a) (2 points). Give example of  $2 \times 2$  non-zero matrices  $A, B, C$  such that  $AB = AC$  but  $B \neq C$ .

**Solution:**

$$A = \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix}, B = \begin{bmatrix} 1 & 2 \\ 3 & 4 \end{bmatrix}, C = \begin{bmatrix} 1 & 2 \\ 1 & 2 \end{bmatrix}, \text{ then } AB = AC = \begin{bmatrix} 1 & 2 \\ 0 & 0 \end{bmatrix}$$

(b) (2 points). Write  $2 \times 2$  invertible matrices  $A$  and  $B$  such that  $A + B$  is not invertible.

**Solution:**

$$A = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}, B = \begin{bmatrix} -1 & 0 \\ 0 & -1 \end{bmatrix}, \text{ then } A + B = \begin{bmatrix} 0 & 0 \\ 0 & 0 \end{bmatrix} \text{ which is not invertible.}$$

(c) (2 points). Write  $3 \times 3$  singular matrices  $A$  and  $B$  such that  $A - B$  is non-singular.

**Solution:**

$$A = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{bmatrix}, B = \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & -1 \end{bmatrix}, \text{ then } A - B = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \text{ which is not singular.}$$

(d) (2 points). **T** or **F**? (Circle your answer) If  $A$  and  $B$  are invertible matrices of same size, then  $AB$  and  $BA$  are both invertible.

**Solution:**

True.

Let  $A^{-1}, B^{-1}$  be the inverse matrices of  $A, B$ , then  $(B^{-1}A^{-1})AB = I$  and  $(A^{-1}B^{-1})BA = I$ , thus  $AB$  and  $BA$  are both invertible.

(e) (2 points). **T** or **F**? (Circle your answer) If  $A^2$  is not invertible, then  $A$  is not invertible.

**Solution:**

True.

The contrapositive is true since  $A$  is invertible,  $A^{-1}A^{-1}AA = I$  gives  $A^2$  is also invertible.

4. [10 points] Find  $LDU$  decomposition of the matrix

$$A = \begin{bmatrix} 1 & -1 & 1 \\ -1 & 3 & -3 \\ -2 & -4 & 7 \end{bmatrix}$$

**Solution:**

Elimination process:

$$\begin{bmatrix} 1 & -1 & 1 \\ -1 & 3 & -3 \\ -2 & -4 & 7 \end{bmatrix} \xrightarrow[l_{31} = -2]{l_{21} = -1} \begin{bmatrix} 1 & -1 & 1 \\ 0 & 2 & -2 \\ 0 & -6 & 9 \end{bmatrix} \xrightarrow{l_{32} = -3} \begin{bmatrix} 1 & -1 & 1 \\ 0 & 2 & -2 \\ 0 & 0 & 3 \end{bmatrix} = U_1$$

$$U_1 = D \cdot U = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & 3 \end{bmatrix} \cdot \begin{bmatrix} 1 & -1 & 1 \\ 0 & 1 & -1 \\ 0 & 0 & 1 \end{bmatrix}$$

$$(a) \ L = \begin{bmatrix} 1 & 0 & 0 \\ l_{21} & 1 & 0 \\ l_{31} & l_{32} & 1 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 \\ -1 & 1 & 0 \\ -2 & -3 & 1 \end{bmatrix}$$

$$(b) \ D = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & 3 \end{bmatrix}$$

$$(c) \ U = \begin{bmatrix} 1 & -1 & 1 \\ 0 & 1 & -1 \\ 0 & 0 & 1 \end{bmatrix}$$

5. [10 points] Solve the system  $A\mathbf{x} = \mathbf{b}$  for

$$A = \begin{bmatrix} 1 & -1 & -1 \\ -2 & 3 & 1 \\ 3 & -7 & 2 \end{bmatrix}, \quad \mathbf{b} = \begin{bmatrix} 1 \\ -1 \\ 1 \end{bmatrix}$$

using the following steps:

(a) (3 points). Compute factorization  $A = LU$ .

First, find upper triangular matrix  $U$ :

$$\begin{bmatrix} 1 & -1 & -1 \\ -2 & 3 & 1 \\ 3 & -7 & 2 \end{bmatrix} \xrightarrow{\substack{R_2 + 2R_1, R_3 - 3R_1 \\ R_3 + 4R_2, R_3 + 4R_2}} \begin{bmatrix} 1 & -1 & -1 \\ 0 & 1 & -1 \\ 0 & 0 & 1 \end{bmatrix} = U$$

Multiplying  $LU$  produces  $A$

$$A = \begin{bmatrix} 1 & -1 & -1 \\ -2 & 3 & 1 \\ 3 & -7 & 2 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 \\ -2 & 1 & 0 \\ 3 & -4 & 1 \end{bmatrix} \begin{bmatrix} 1 & -1 & -1 \\ 0 & 1 & -1 \\ 0 & 0 & 1 \end{bmatrix} = LU$$

(b) (3 points). Solve  $L\mathbf{y} = \mathbf{b}$  by forward substitution.

$$\begin{bmatrix} 1 & 0 & 0 \\ -2 & 1 & 0 \\ 3 & -4 & 1 \end{bmatrix} \begin{bmatrix} y_1 \\ y_2 \\ y_3 \end{bmatrix} = \begin{bmatrix} 1 \\ -1 \\ 1 \end{bmatrix} \rightarrow \begin{cases} y_1 = 1 \\ -2y_1 + y_2 = -1 \\ 3y_1 - 4y_2 + y_3 = 1 \end{cases} \rightarrow \begin{cases} y_1 = 1 \\ y_2 = 1 \\ y_3 = 2 \end{cases}$$

(c) (3 points). Solve  $U\mathbf{x} = \mathbf{y}$  by backward substitution.

$$\begin{bmatrix} 1 & -1 & -1 \\ 0 & 1 & -1 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 1 \\ 1 \\ 2 \end{bmatrix} \rightarrow \begin{cases} x_1 - x_2 - x_3 = 1 \\ x_2 - x_3 = 1 \\ x_3 = 2 \end{cases} \rightarrow \begin{cases} x_1 = 6 \\ x_2 = 3 \\ x_3 = 2 \end{cases}$$

(d) (1 point). What is the solution of  $A\mathbf{x} = \mathbf{b}$ ?

$$\begin{cases} x_1 = 6 \\ x_2 = 3 \\ x_3 = 2 \end{cases} \quad \text{from part (c) is the solution of both } U\mathbf{x} = \mathbf{y} \text{ and } A\mathbf{x} = \mathbf{b}.$$

6. [10 points] Forward elimination changes  $A\mathbf{x} = \mathbf{b}$  to the system  $R\mathbf{x} = \mathbf{d}$ . If the process of elimination subtracted 3 times row 1 from row 2 and then 5 times row 1 from row 3, what matrix connects  $R$  and  $\mathbf{d}$  to the original  $A$  and  $\mathbf{b}$ ? (That is, find  $E$  such that  $R = EA$  and  $E\mathbf{b} = \mathbf{d}$ ).

Solution:

$$\text{Here, } E_{21} = \begin{bmatrix} 1 & 0 & 0 \\ -3 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \text{ and } E_{31} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ -5 & 0 & 1 \end{bmatrix}$$

$$\text{Hence, the matrix that connects } R \text{ and } \mathbf{d} \text{ to the original } A \text{ and } \mathbf{b} \text{ is } E = E_{31}E_{21} = \begin{bmatrix} 1 & 0 & 0 \\ -3 & 1 & 0 \\ -5 & 0 & 1 \end{bmatrix}$$

7. [10 points] Given matrix  $A = \begin{bmatrix} 0 & 3 & 4 \\ 1 & 2 & 3 \\ -3 & -7 & 8 \end{bmatrix}$ ,

(a) (5 points). Show that  $A$  has no  $LU$  decomposition.

**Solution:**

The first pivot of the matrix  $A$  is 0 and hence  $A = LU$  decomposition fails as we require a row interchange to create a nonzero pivot.

(b) (5 points). Find the decomposition  $PA = LU$ , where  $P$  is an elementary permutation matrix.

**Solution:**

$P_{12}$  interchanges row  $R_1$  and  $R_2$

$$P_{12}A = \begin{bmatrix} 0 & 1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 0 & 3 & 4 \\ 1 & 2 & 3 \\ -3 & -7 & 8 \end{bmatrix} = \begin{bmatrix} 1 & 2 & 3 \\ 0 & 3 & 4 \\ -3 & -7 & 8 \end{bmatrix}$$

$E_{31}$  adds 3 times  $R_1$  to  $R_3$

$$E_{31}P_{12}A = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 3 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 2 & 3 \\ 0 & 3 & 4 \\ -3 & -7 & 8 \end{bmatrix} = \begin{bmatrix} 1 & 2 & 3 \\ 0 & 3 & 4 \\ 0 & -1 & 17 \end{bmatrix}$$

$E_{32}$  adds  $\frac{1}{3}$  times  $R_2$  to  $R_3$

$$E_{32}E_{31}P_{12}A = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & \frac{1}{3} & 1 \end{bmatrix} \begin{bmatrix} 1 & 2 & 3 \\ 0 & 3 & 4 \\ 0 & -1 & 17 \end{bmatrix} = \begin{bmatrix} 1 & 2 & 3 \\ 0 & 3 & 4 \\ 0 & 0 & \frac{47}{3} \end{bmatrix}$$

Thus we have

$$PA = LU = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ -3 & -\frac{1}{3} & 1 \end{bmatrix} \begin{bmatrix} 1 & 2 & 3 \\ 0 & 3 & 4 \\ 0 & 0 & \frac{47}{3} \end{bmatrix}$$

8. [10 points] Let  $S = \begin{bmatrix} 1 & 1 & 2 \\ 1 & 3 & 8 \\ 2 & 8 & 23 \end{bmatrix}$  be a symmetric matrix. Find the symmetric factorization of  $S$

as  $S = LDL^T$ .

**Solution:**

Since  $S$  is symmetric, we will find the multipliers and the pivots only. The upper triangular matrix  $U$  is:

$$\begin{bmatrix} 1 & 1 & 2 \\ 1 & 3 & 8 \\ 2 & 8 & 23 \end{bmatrix} \xrightarrow[\substack{R_3 - 2R_1}]{R_2 - R_1} \begin{bmatrix} 1 & 1 & 2 \\ 0 & 2 & 6 \\ 0 & 6 & 19 \end{bmatrix} \xrightarrow{R_3 - 3R_2} \begin{bmatrix} 1 & 1 & 2 \\ 0 & 2 & 6 \\ 0 & 0 & 1 \end{bmatrix} = U$$

So,  $l_{21} = 1, l_{31} = 2$  and  $l_{32} = 3$ . Also pivot1=1, pivot2=2 and pivot3=1. Then:

$$S = LDL^T = \begin{bmatrix} 1 & 0 & 0 \\ l_{21} & 1 & 0 \\ l_{31} & l_{32} & 1 \end{bmatrix} \begin{bmatrix} P_1 & 0 & 0 \\ 0 & P_2 & 0 \\ 0 & 0 & P_3 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 \\ l_{21} & 1 & 0 \\ l_{31} & l_{32} & 1 \end{bmatrix}^T = \begin{bmatrix} 1 & 0 & 0 \\ 1 & 1 & 0 \\ 2 & 3 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 1 & 2 \\ 0 & 1 & 3 \\ 0 & 0 & 1 \end{bmatrix}$$



9. [10 points] (A) True or False. Circle your answer and justify it by showing your work (4 points).

(a) **T F:** Let  $A$  be any square matrix, then  $A^T A$ ,  $AA^T$ , and  $A + A^T$  are all symmetric.

**Solution:** True. To check for symmetry, take the transpose:

$(A^T A)^T = A^T (A^T)^T = A^T A$ , where we used the fact that a transpose of a product is the *reversed* product of the transpose and the fact that transposing twice does nothing to  $A$ .

$(AA^T)^T = (A^T)^T A^T = AA^T$

$(A + A^T)^T = A^T + (A^T)^T = A^T + A = A + A^T$ , where we have used the fact that matrices commute under addition.

Thus, each of these matrices is symmetric as they equal their respective transposes.

(b) **T F:** If  $S$  is invertible, then  $S^T$  is also invertible.

**Solution:** True. If we can come up with an inverse for  $S^T$ , then this will show  $S^T$  is invertible. But notice that since  $S$  is invertible,  $SS^{-1} = S^{-1}S = I_n$  (the  $n \times n$  identity matrix), and so we may transpose these two equations to give us:  $(SS^{-1})^T = (I_n)^T$  and  $(S^{-1}S)^T = (I_n)^T$ , but this means  $(S^{-1})^T S^T = I_n$  and  $S^T (S^{-1})^T = I_n$  (since  $I_n$  is symmetric,  $(I_n)^T = I_n$ ), and this demonstrates that the matrix  $(S^{-1})^T$  is a left and right (and hence *the*) inverse for  $S^T$ , from which we may conclude that  $S^T$  is invertible.

(c) **T F:** If a row exchange is required to reduce matrix  $A$  into upper triangular form  $U$ , then  $A$  can not be factored as  $A = LU$ .

**Solution:** True. If we obtained  $U$  by using a row exchange, then in constructing  $L$  we must apply the inverse row exchange. However, this will result in an  $L$  that is not lower triangular, and hence  $A$  is not of the form  $A = LU$  with  $L$  lower triangular. (However, as mentioned in the textbook, any matrix can be factored as  $PA = LU$  for some appropriate exchange matrix  $P$  applied to  $A$  prior to factorization)

(d) **T F:** Suppose  $A$  reduces to upper triangular  $U$  but  $U$  has a 0 in pivot position, then  $A$  has no  $LDU$  factorization.

**Solution:** False. If we write  $A = LU$ , but  $U$  contains a 0 pivot, we will be able to place any real number we want in the corresponding diagonal entry to obtain a valid  $LDU$  factorization. However, this factorization will not in general be unique.

(B) Solve the following problems showing your work (6 points).

- (a) A symmetric matrix  $S$  reduces to  $\begin{bmatrix} 3 & 9 \\ 0 & 7 \end{bmatrix}$  after performing row operations (except permutations), write the  $LDU$  decomposition of  $S$ .

**Solution:** Since  $S$  is symmetric and a single row operation reduced it to the above, we see that this operation must have turned a lower-left 9 into a 0. This corresponds to three times the first row. Hence, to undo the process we add three times the first row to obtain:

**Answer:**  $S = \begin{bmatrix} 3 & 9 \\ 9 & 16 \end{bmatrix}$

- (b) Let  $A$  and  $B$  be two symmetric matrices of same size. Which of the followings are symmetric?  $A + B$ ,  $A - B$ ,  $A^2$ ,  $AB$ ,  $ABA$ ,  $ABAB$ ,  $ABABA$ .

**Solution:** In general, sums, differences, powers, and palindromes (reads the same forwards as backwards) of symmetric matrices are symmetric. Hence,  $A + B$ ,  $A - B$ ,  $A^2$ ,  $ABA$ , and  $ABABA$  are symmetric when  $A$  and  $B$  are. However,  $(AB)^T = B^T A^T = BA$  and  $(ABAB)^T = B^T A^T B^T A^T = BABA$ , so  $AB$  and  $ABAB$  are not symmetric in general.

- (c) Write the inverse of the permutation matrix  $P = \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 1 & 0 & 0 \end{bmatrix}$ .

**Solution:**  $P$  places row 1 in row 3, row 3 in row 2, and row 2 in row 1. Hence, we need  $P^{-1}$  to place row 3 in row 1, row 2 in row 3, and row 1 in row 2. This matrix is:

**Answer:**  $P^{-1} = \begin{bmatrix} 0 & 0 & 1 \\ 1 & 0 & 0 \\ 0 & 1 & 0 \end{bmatrix}$ .

10. [10 points] Determine if the set consisting of

- (a) all  $(x, y, z) \in \mathbb{R}^3$  with  $x = y + z$  is a subspace of  $\mathbb{R}^3$
- (b) all  $(x, y, z) \in \mathbb{R}^3$  with  $x + z = 2018$  is a subspace of  $\mathbb{R}^3$
- (c) all  $2 \times 2$  symmetric matrices is a subspace of  $M_{22}$ . (Here  $M_{22}$  is the vector space of all  $2 \times 2$  matrices.)
- (d) all polynomials of degree exactly 3 is a subspace of  $P_5$ . (Here  $P_5$  is the vector space of all polynomials  $a_5x^5 + a_4x^4 + a_3x^3 + a_2x^2 + a_1x + a_0$  of degree less than or equal to 5.)

**Solution.**

(a) Yes.

$$\begin{bmatrix} a+b \\ a \\ b \end{bmatrix} + \begin{bmatrix} c+d \\ c \\ d \end{bmatrix} = \begin{bmatrix} (a+c) + (b+d) \\ (a+c) \\ (b+d) \end{bmatrix},$$
$$r \begin{bmatrix} a+b \\ a \\ b \end{bmatrix} = \begin{bmatrix} ra+rb \\ ra \\ rb \end{bmatrix}, \quad \text{for any } r \in \mathbb{R}.$$

(b) No, because the zero vector does not belong to the given set.

(c) Yes.

$$\begin{bmatrix} a & b \\ b & c \end{bmatrix} + \begin{bmatrix} d & f \\ f & g \end{bmatrix} = \begin{bmatrix} a+d & b+f \\ b+f & c+g \end{bmatrix}$$

is a symmetric matrix. Also, for any  $r \in \mathbb{R}$

$$r \begin{bmatrix} a & b \\ b & c \end{bmatrix} = \begin{bmatrix} ra & rb \\ rb & rc \end{bmatrix}$$

is a symmetric matrix.

(d) No. All polynomials of degree exactly 3 is not a linear space. For instance, take  $q = x^3 + x$  and  $p = -x^3$ , then  $q + p = x$  is a polynomial of degree 1.